

# Grey and Red squirrel Least Cost Pathway in Kielder Forest

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A Machine Learning and GIS-Based approach  
LIFE14 NAT/UK/000467

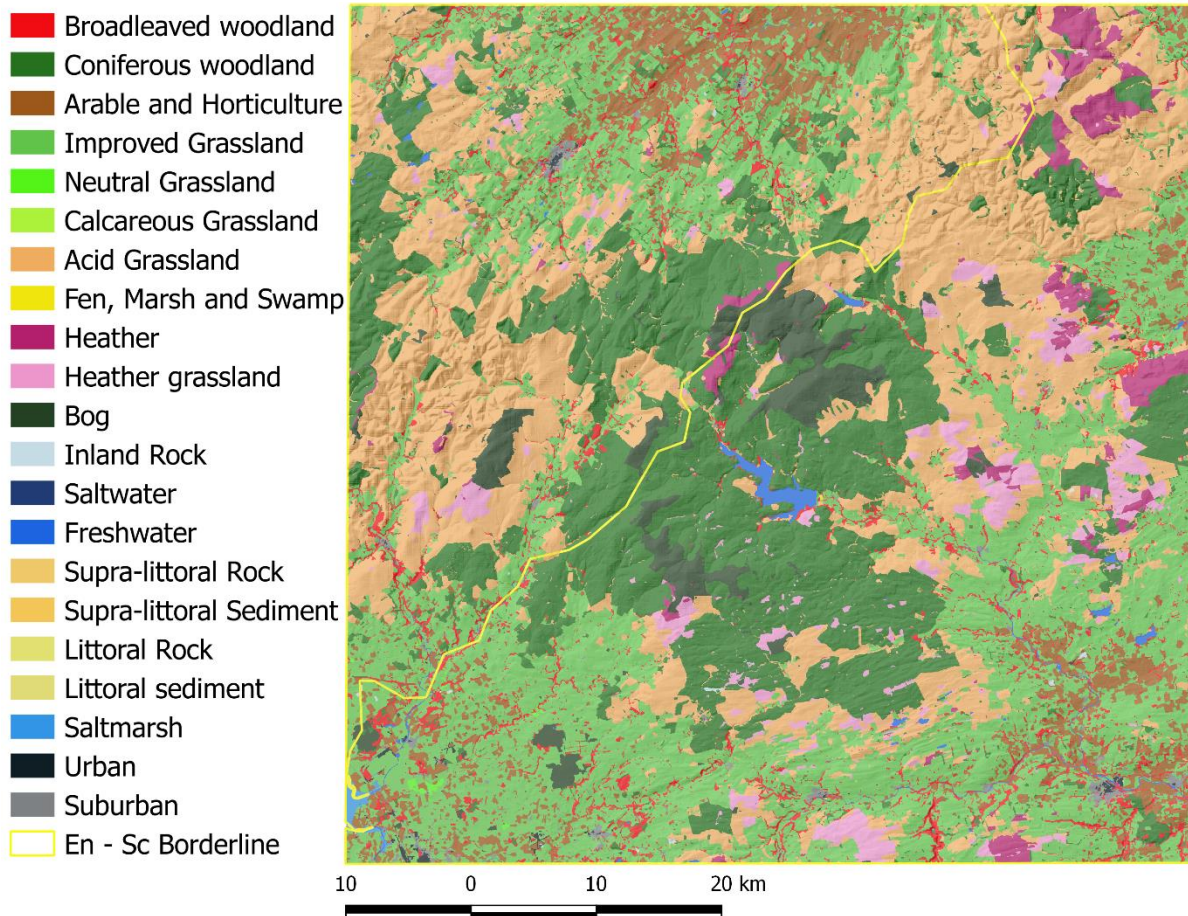
Simone Caruso, Zelda van der Waal and Aileen Mill  
(Newcastle University)



# Study area: Kielder Forest



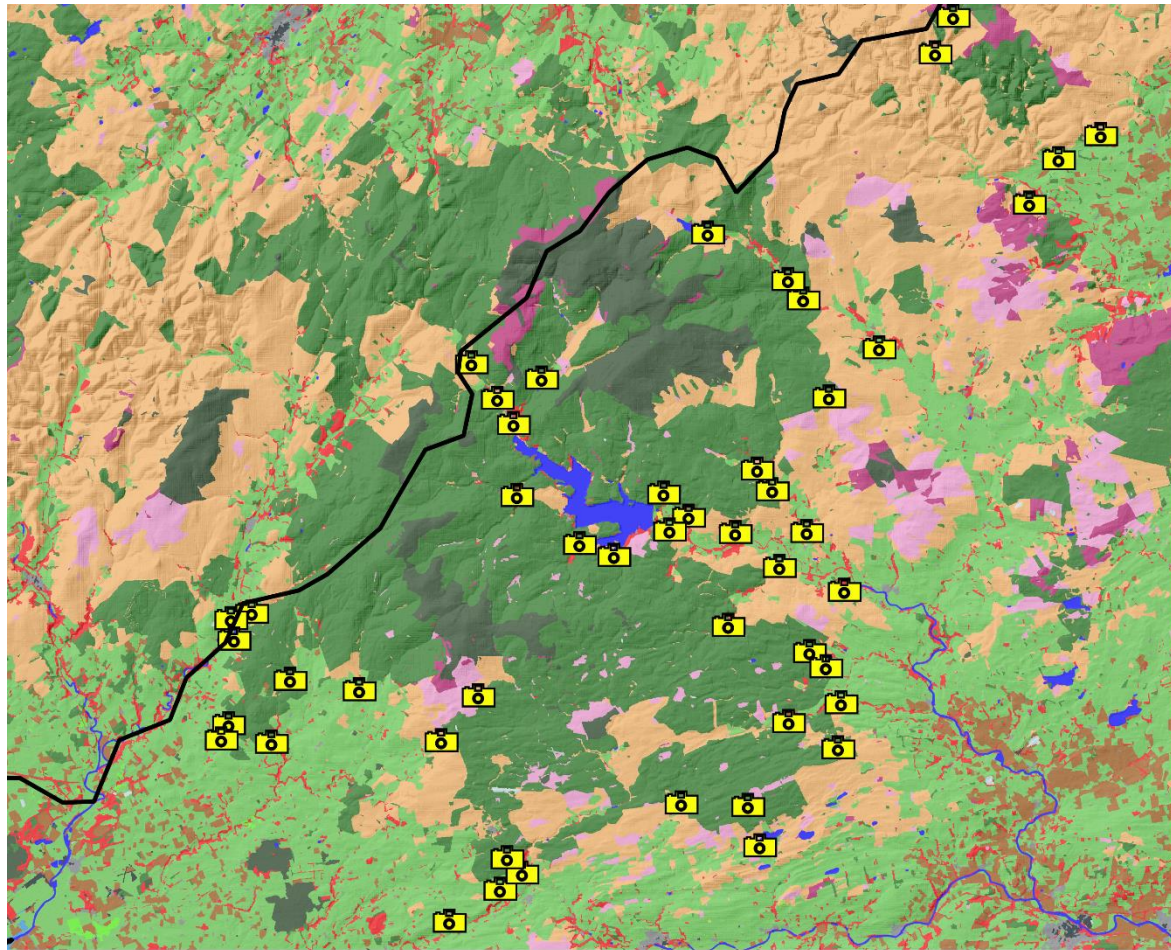
## Land Cover Map 2015



- **LCM 2015** classification at 25m resolution
- Largest Human-made woodland complex in England  
ca. 80% Conifer: mainly Sitka and Norway Spruce
- High landscape fragmentation and heterogeneity
- **Patchy landscape**



# Camera Traps Network



## NWT's Early Warning Detection System

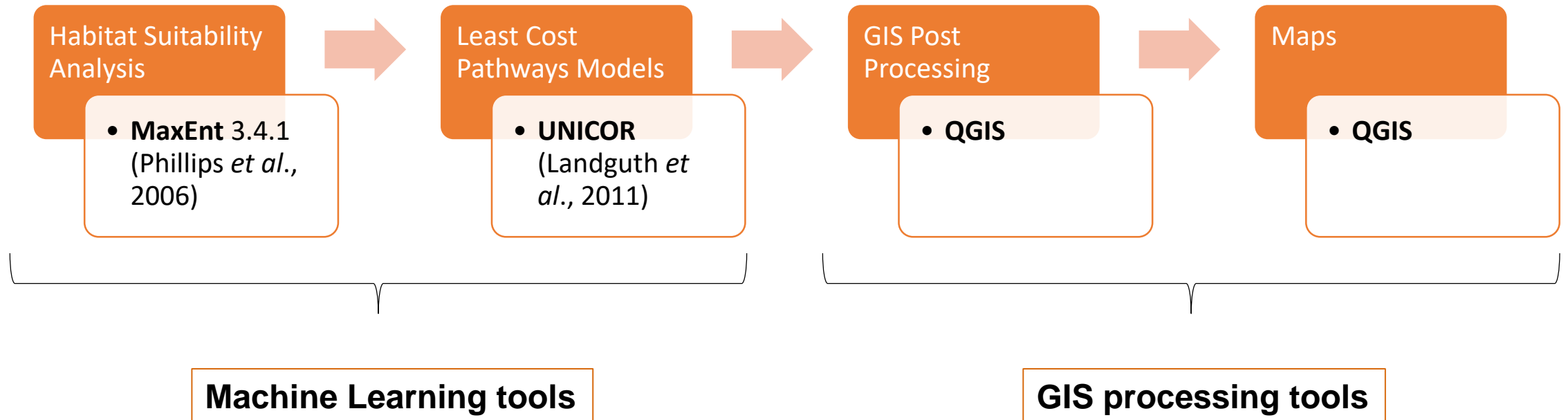
- **50** Camera Traps across Kielder Forest since 2012
- Spacing configuration **based on Expert – Opinion**

# Aims of the study



- Identify the **most likely routes of movements of grey and red squirrels** across North England landscape and across South of Scotland, by developing Least Cost Pathways models (LCPs)
- Evaluate the **spatial configuration** of the camera traps network in order to figure out how well the monitoring programme is working and if changes are needed
- Identify **key areas** that might be **safeguarded from invasions**
- Identify **areas** where red squirrel **conservation efforts should be focused**
- Provide maps and tools useful to inform the management strategy
- Better understanding of the landscape use for grey and red squirrels

# Analytical Process



# Habitat Suitability Analysis

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## What it is?

Relationship between the occurrence record of a target species and the environment

**Habitat Suitability Index** : from **0** (*unsuitable habitat*) to **1** (*high suitable, optimal habitat*)

## How?

**MaxEnt Algorithm**: Allow to compute a habitat suitability model using ***presence only data***, demographic parameter (dispersal) and the ***environmental variables*** of the place where the species has been recorded

# Why MaxEnt?



Widely used and well-accepted  
**presence – only** modelling process

Data prepared in QGIS environment  
at a resolution of **25m**



## **INPUT DATA**

### **Red and Grey squirrel occurrence records**

- RSNE annual monitoring system (2013 – 2018) - England
- NBN Atlas (2014 – 2018) - Scotland

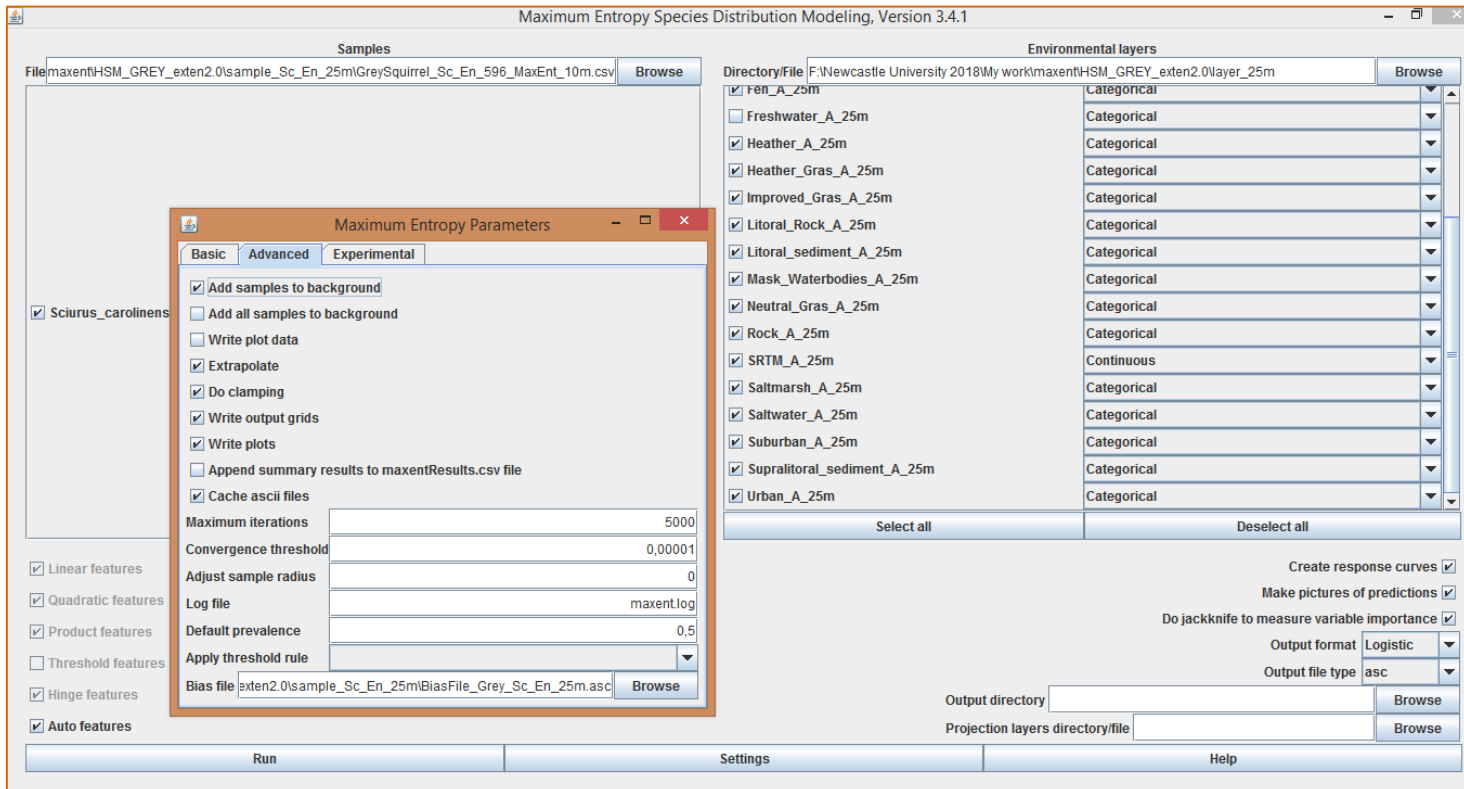
### **Environmental variable**

- Land Cover Map 2015
- SRTM Altitude layer

### **Demographic parameter**

- Dispersal

# MaxEnt 3.4.1



- Occurrence records
- Environmental variables
- Background data default (10.000 points)
- Number of Maximum Interaction 5000
- Bias File (Sampling bias correction)
- **Logistic Output**



**HSIndex = probability of presence**  
*(under some circumstances)*

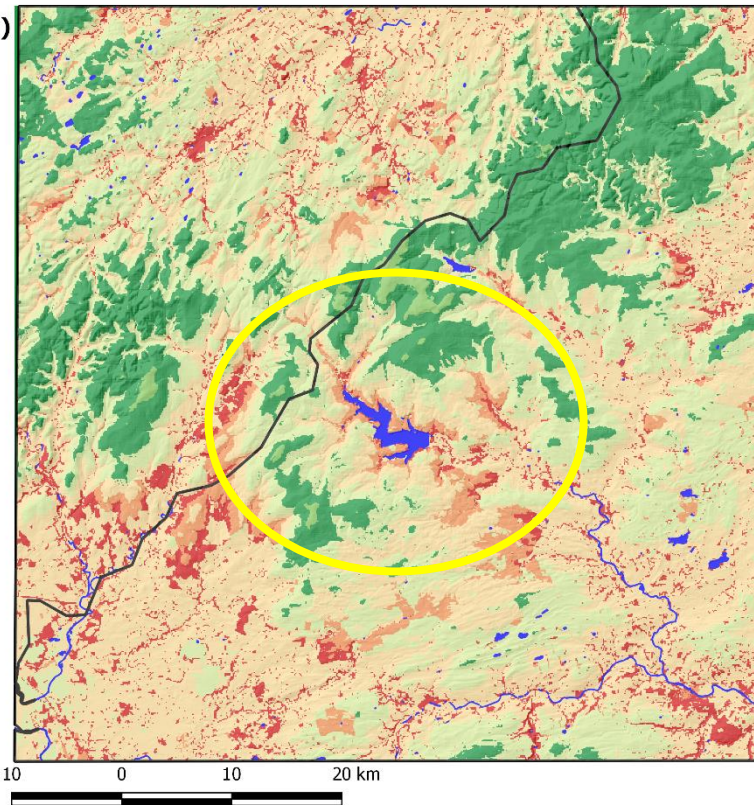
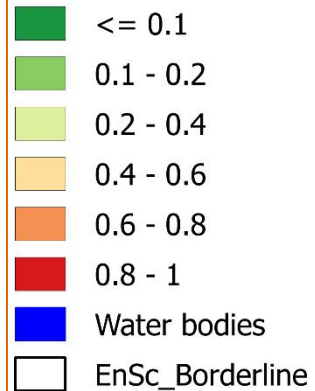


# MaxEnt Outcomes



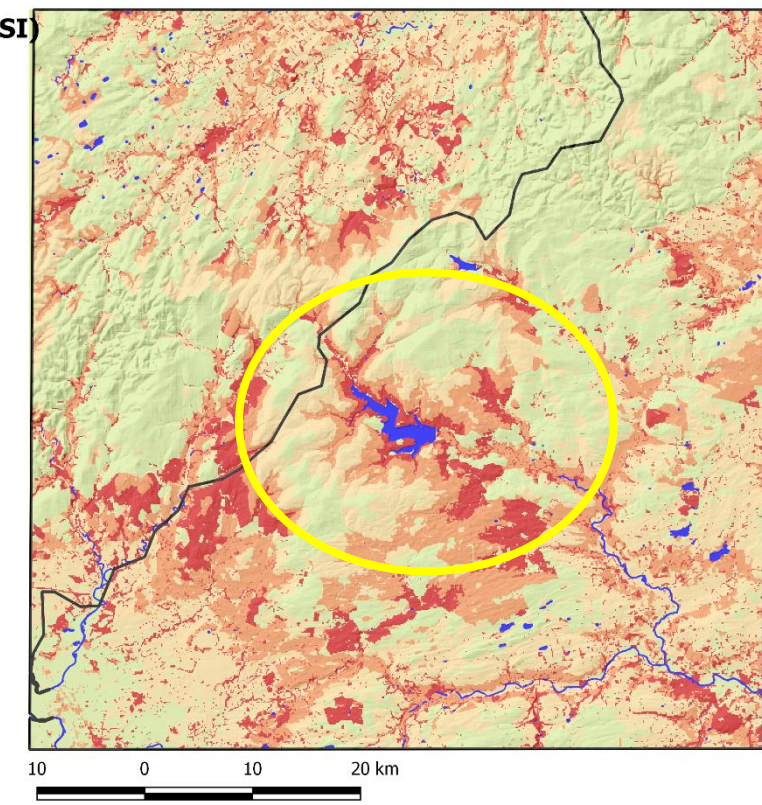
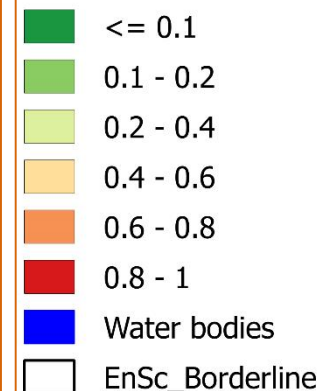
## Habitat Suitability Map - Grey Squirrel

Habitat Suitability Index (HSI)



## Habitat Suitability Map - Red squirrel

Habitat Suitability Index (HSI)



# Least Cost Pathway



## What it is?

Least Cost Pathway models are tools to identify the most likely used routes of a species between presence points across the landscape

Widely used as **landscape connectivity** tool, for mapping **ecological corridors** and to predict animal movements

# UNICOR

(Universal Corridor Network Simulator)

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## What it is?

Species connectivity and corridor identification tool (Landguth *et al.*, 2011)

## What it does?

Compute a **single path** or **all the shorter paths** between points on a landscape, to create a **connectivity graph** which can be used to highlight:

- Least Cost Pathways
- Bottleneck
- Areas of high connectivity
- Ecological barriers

# UNICOR

(Universal Corridor Network Simulator)

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## How it works?

UNICOR requires two input files:

1. Species **presence points** (nodes) – Start and End points between paths
2. Landscape **Resistance surface**



Is a cost-surface where each pixel is given a weight (**resistance value**) which represents the “cost” of movement across that pixel

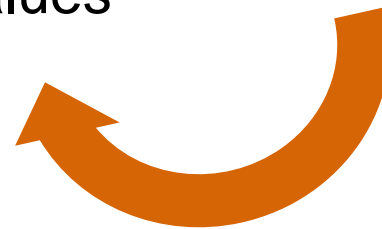
## How to get the Resistance Surface?

Habitat Suitability Index **inversely linked** to the landscape Resistance



Higher habitat suitability values implies  
lower landscape resistance values  
and lower habitat suitability values  
refers to higher resistance values

**Reciprocal Cubic Function** of the  
Habitat Suitability Index  
for each pixel of the  
Habitat Suitability map





# UNICOR Outcomes

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Connectivity network composed of multiple paths in which each represent a **likely corridor of movement with different strength depending on the cost of moving** within the landscape across the resistance surface

## QGIS Post Processing:

- The whole connectivity network over the Resistance surface
- The main and strongest connections
- Bottlenecks and areas of high connectivity – (Connectivity Density)
- Early warning detection system over the Least Cost Pathways map

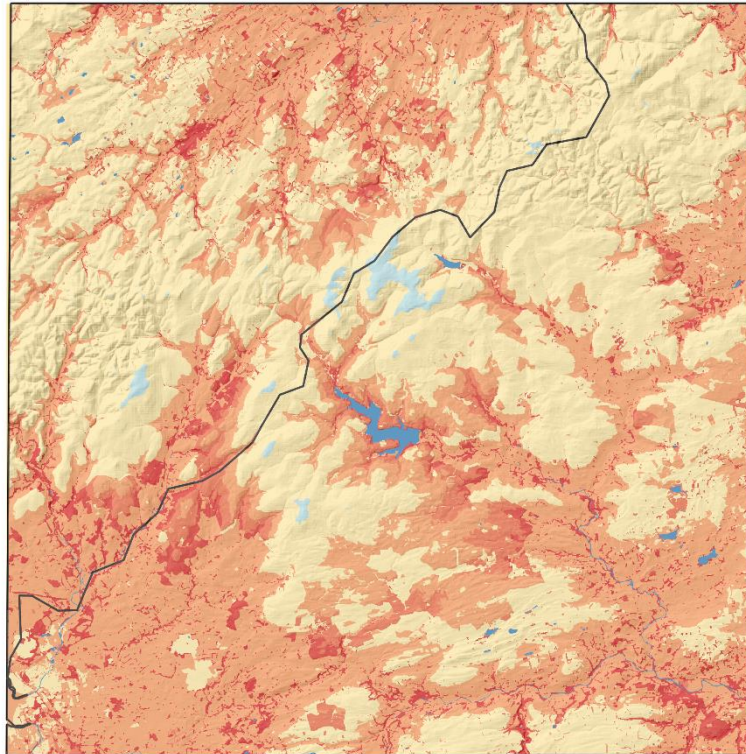
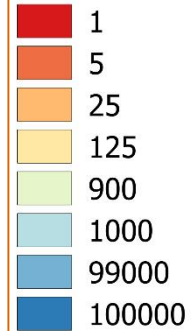
# Resistance Surface



## Landscape Resistance Surface Grey Squirrel

EnSc\_Borderline

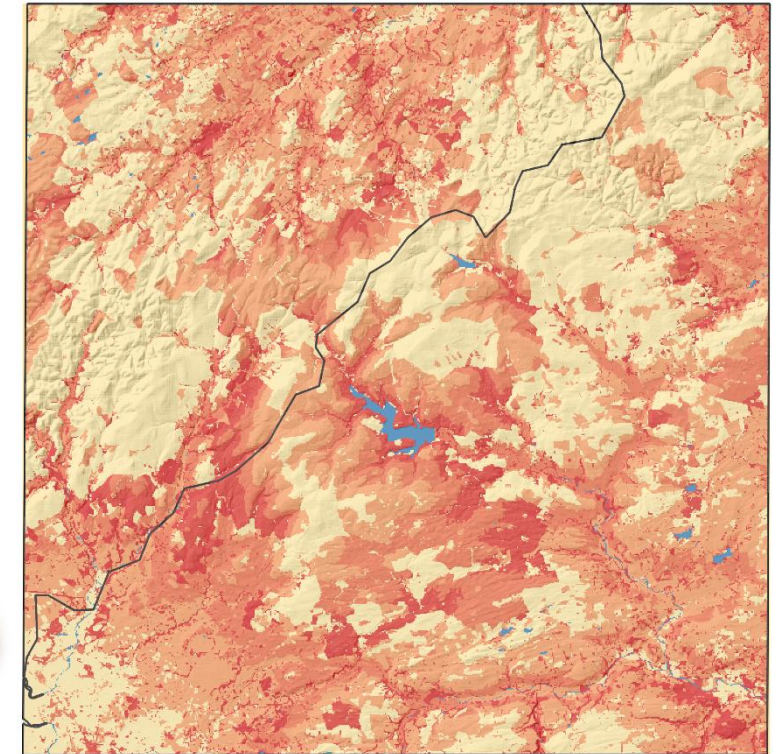
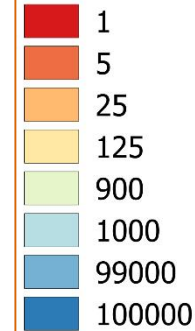
### Resistance Values



## Landscape Resistance Surface Red Squirrel

EnSc\_Borderline

### Resistance Values





# Resistance Surface

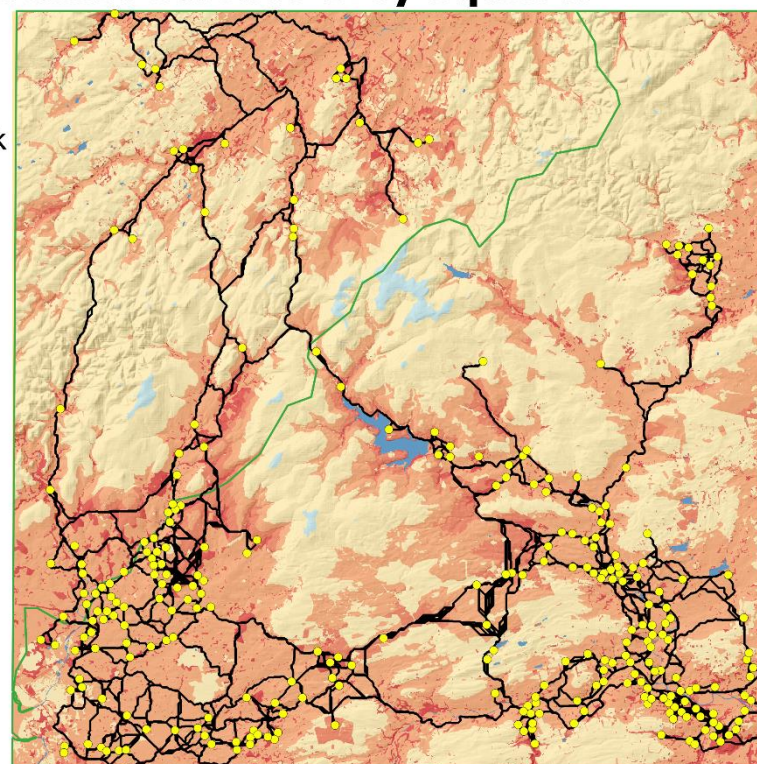


## Landscape Resistance Surface Grey Squirrel

- Presence Points
- EnSc\_Borderline
- Least Cost Network

### Resistance Values

- 1
- 5
- 25
- 125
- 900
- 1000
- 99000
- 100000



10 0 10 20 km

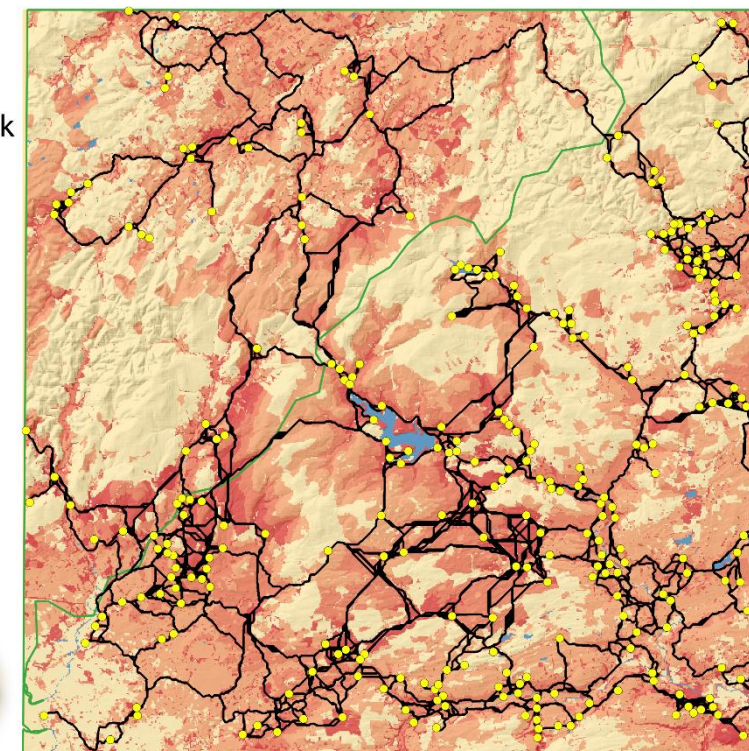


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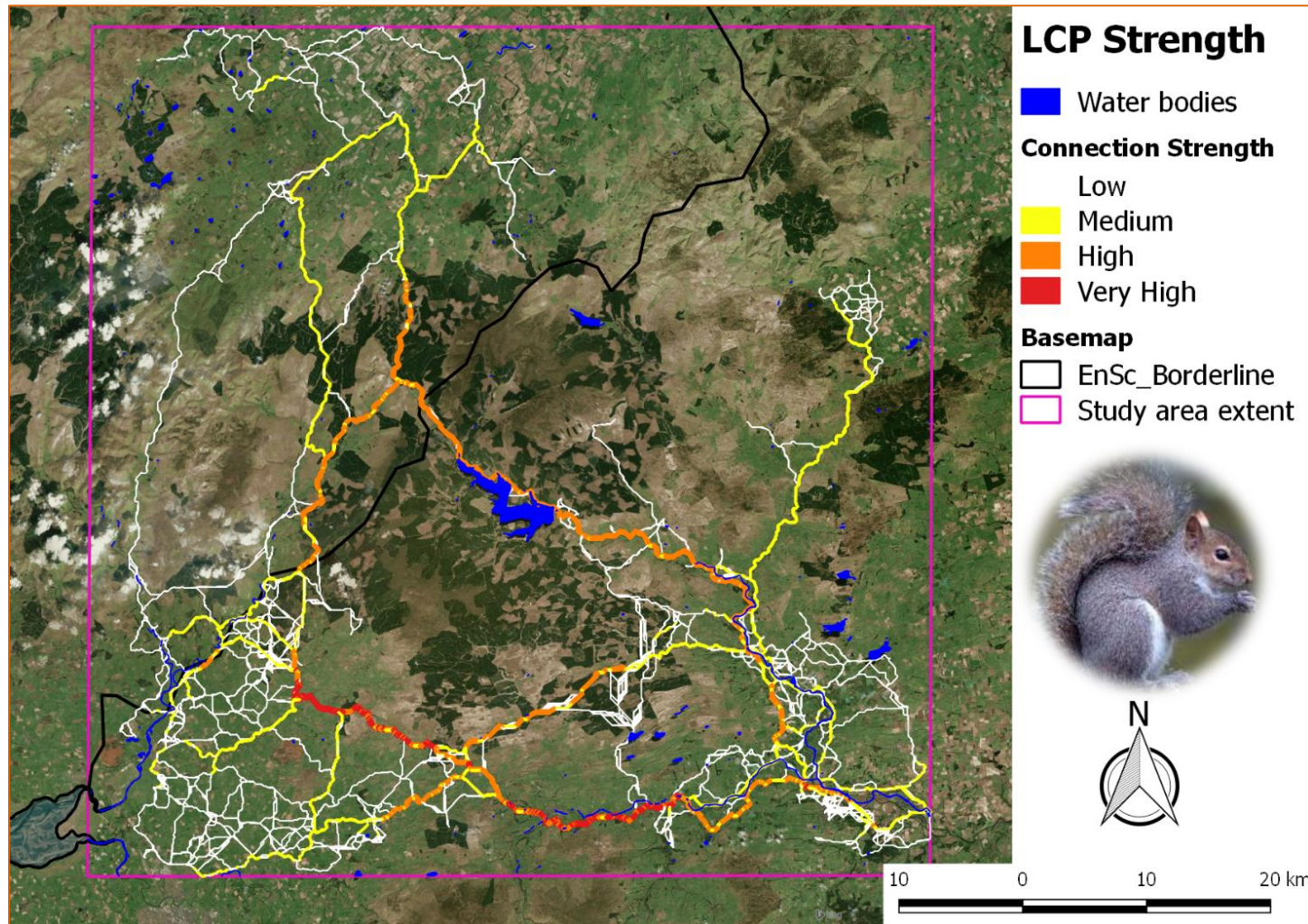


10 0 10 20 km



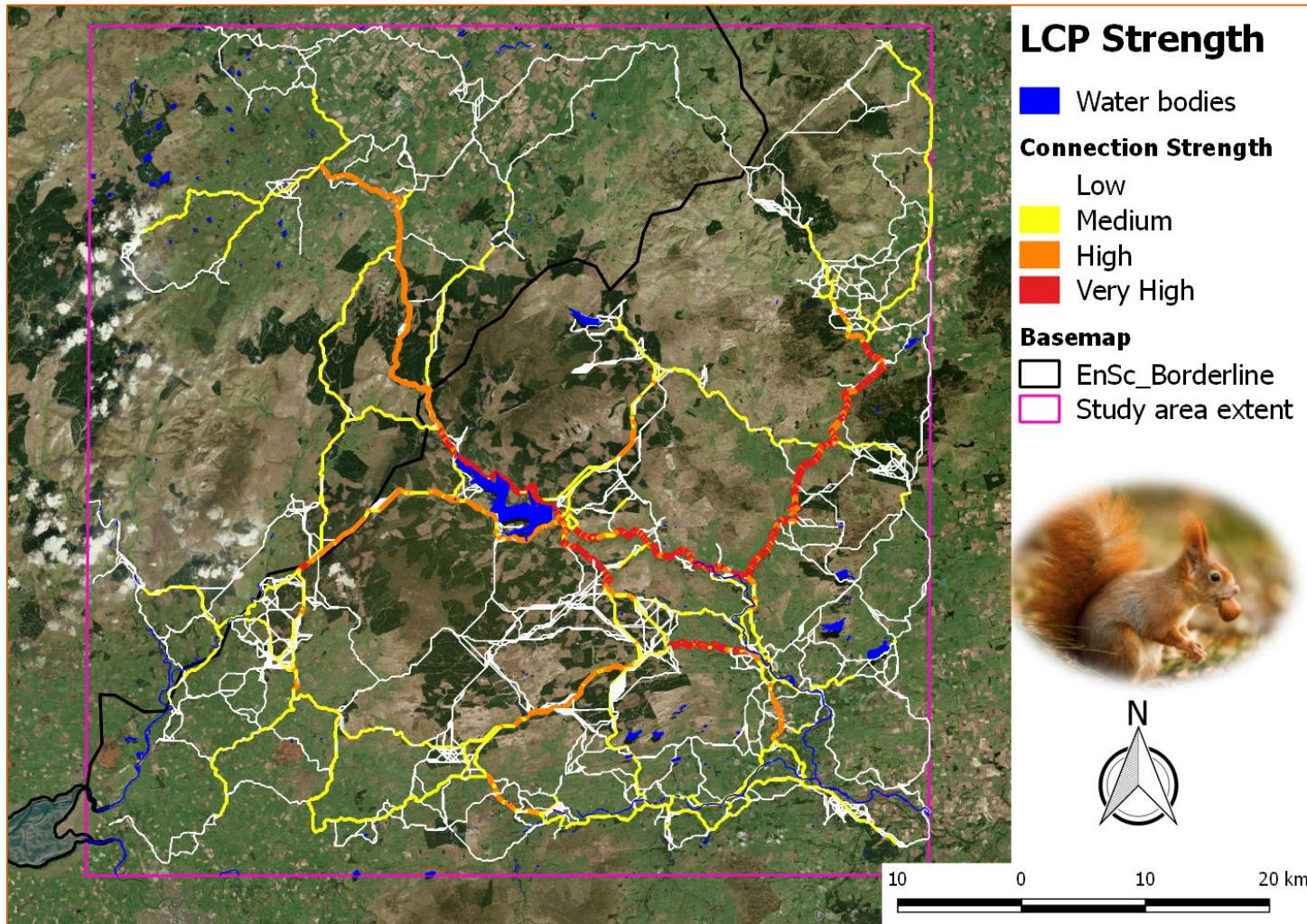


# Strongest Least Cost connections





# Strongest Least Cost connections





# Connectivity Density Analysis

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- **Bottlenecks**
- **Areas of High Connectivity**

# Connectivity Density Analysis



## Connectivity Density Grey Squirrel

EnSc\_Borderline

Water bodies

### Connectivity Density

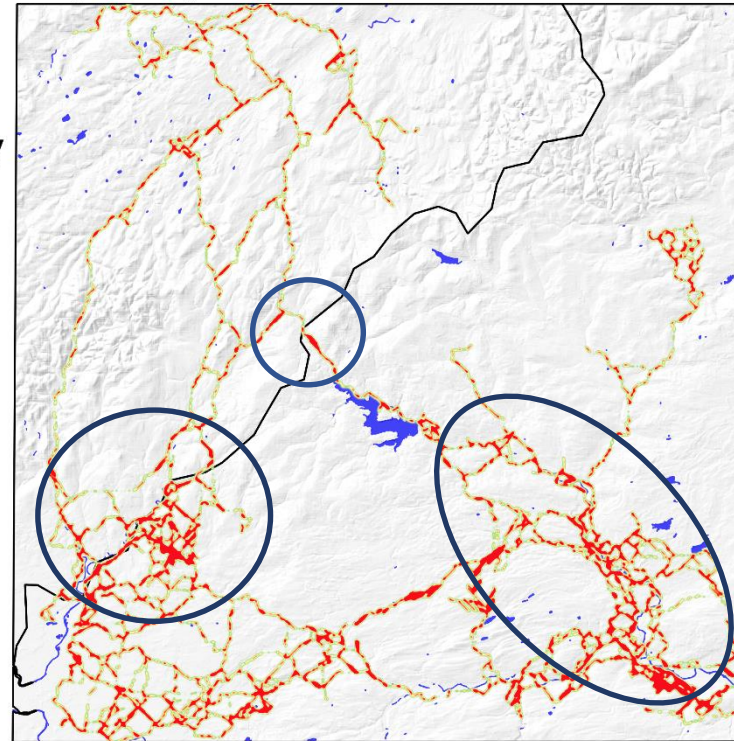
Low

Limited

Moderate

High

Very high



## Connectivity Density Red Squirrel

EnSc\_Borderline

Water bodies

### Connectivity Density

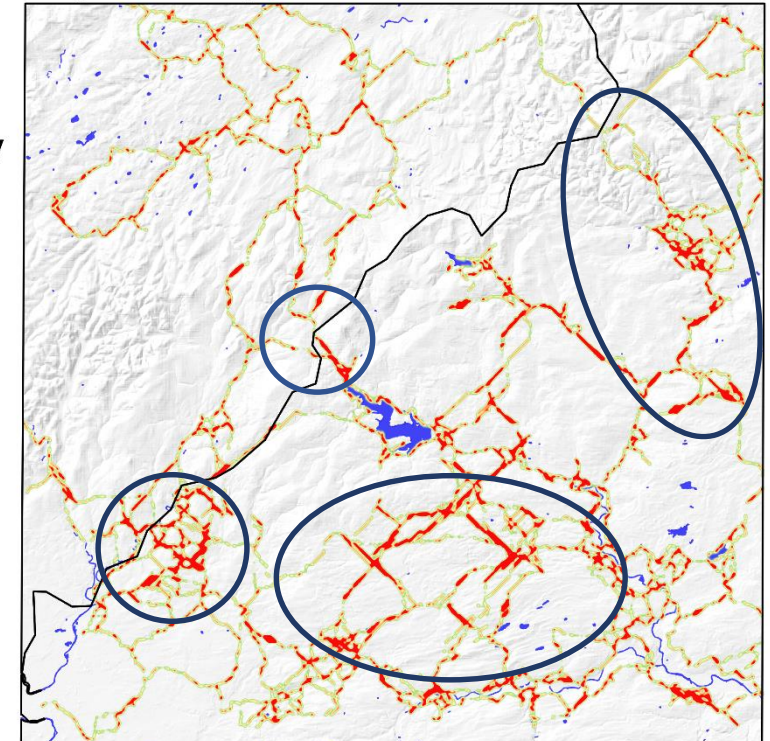
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# Early Warning Detection System



Squirrel Observed\_QMOct17

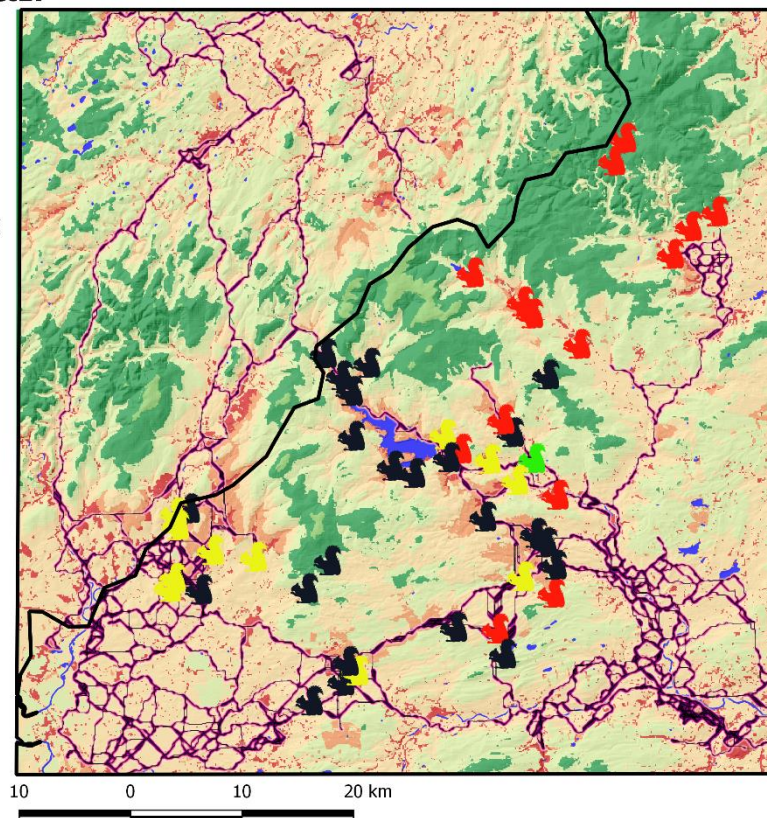
- Grey
- None
- Red
- Grey and Red
- Least Cost Network

Habitat Suitability Index

- $\leq 0.1$
- 0.1 - 0.2
- 0.2 - 0.4
- 0.4 - 0.6
- 0.6 - 0.8
- 0.8 - 1

Connectivity Density

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- Limited
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- EnSc\_Borderline



Squirrel Observed\_QMOct17

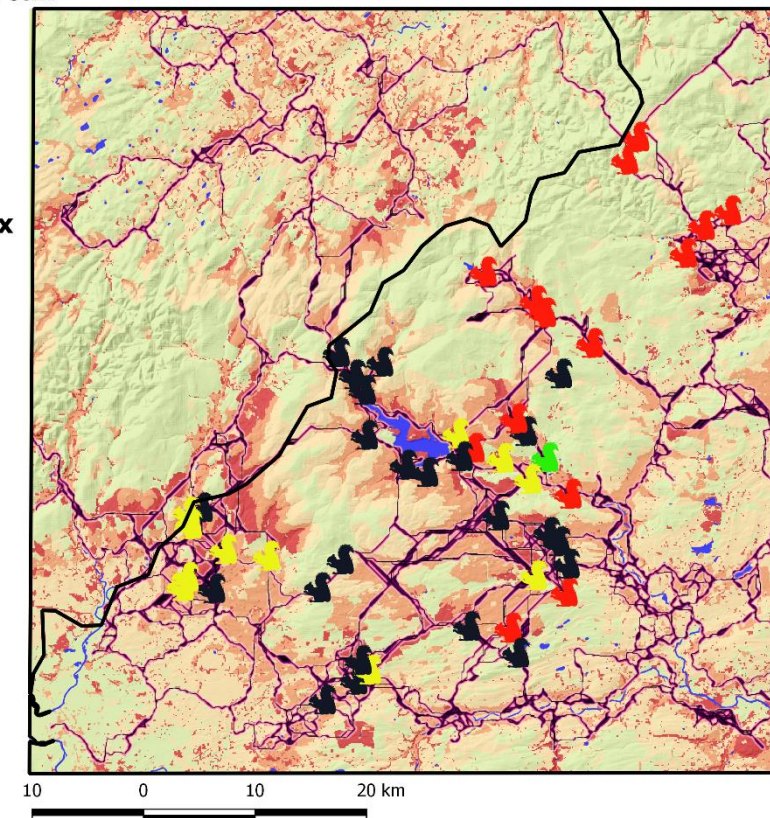
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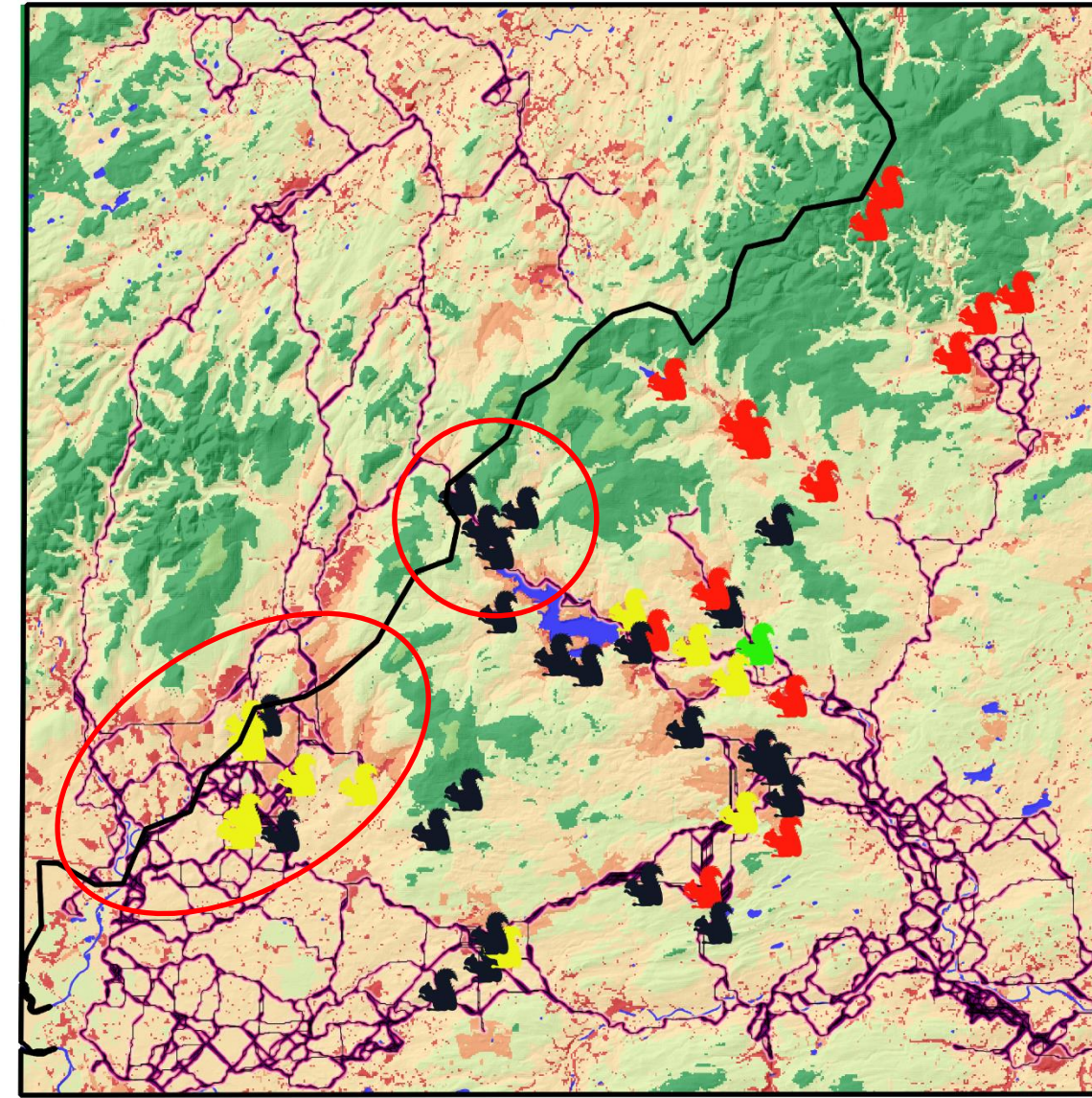
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
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






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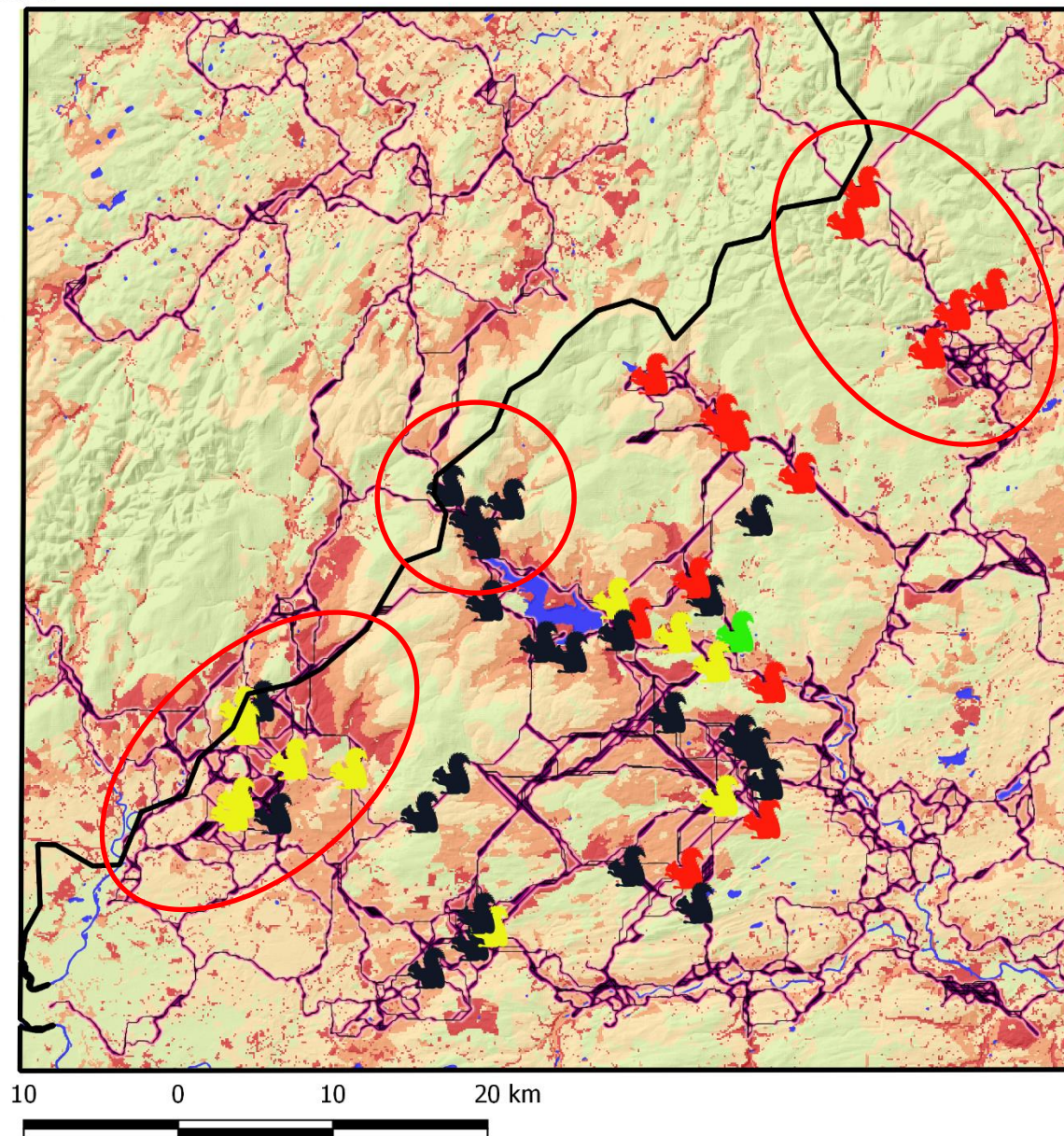
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# Conclusion

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1. Kielder Forest is an optimal habitat for red squirrel, but it is still well permeable to grey squirrel invasions
2. Landscape around Kielder Forest is well connected and the strongest connections for grey squirrel follows the two main river valleys
3. Areas of high connectivity density shows where control / monitoring efforts should be focused in preventing and detecting new invasions at an early stage
4. Three areas of high importance on the borderline with the South of Scotland that need to be defended from invasions coming from the North
5. Camera traps network falls into the predicted corridors used by squirrels
6. The Machine Learning approach gave value to the Expert-Opinion based approach in evaluating the spatial configuration of the detection system
7. Maps and tools useful to practitioners to improve the monitoring system
8. Driving the making-decision process to address the best monitoring strategy
9. Surveys into the main block of woodland in Kielder Forest may be useful to improve the model
10. A strict collaboration between English and Scottish partners is highly recommended

# Acknowledgments

Modelling Evidence and Policy at Newcastle University



Red Squirrel Northern England



Saving Scotland's Red Squirrel



RSU Knowledge Fair 2019



# Thank you!



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