

Grey and Red squirrel Least Cost Pathway in Kielder Forest

A Machine Learning and GIS-Based approach
LIFE14 NAT/UK/000467

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(Newcastle University)

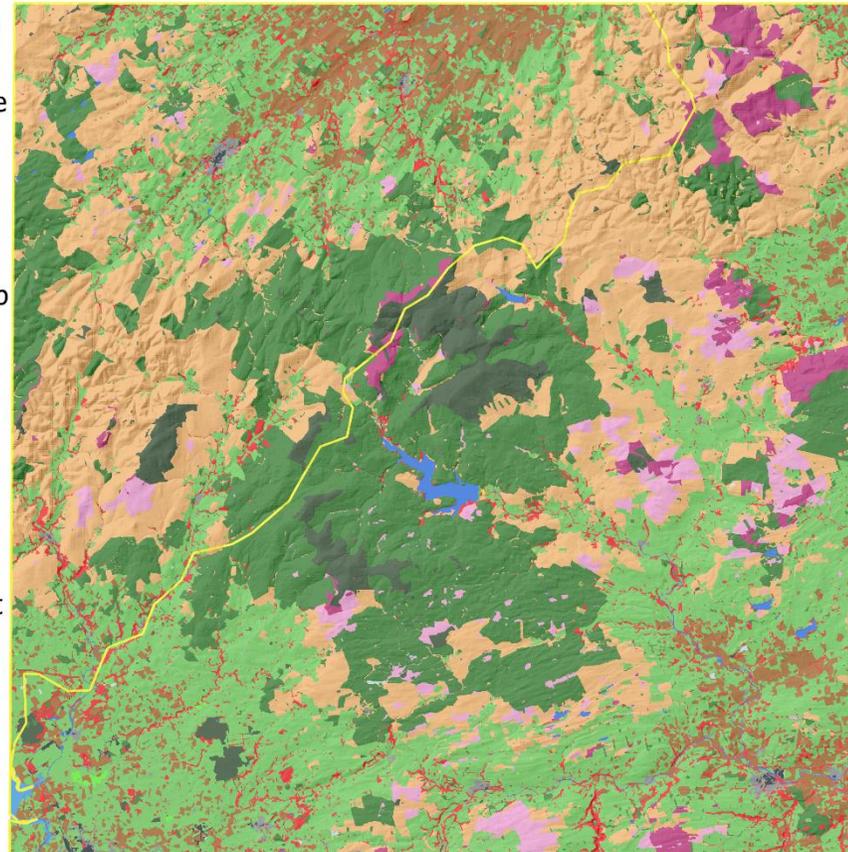


Study area: Kielder Forest



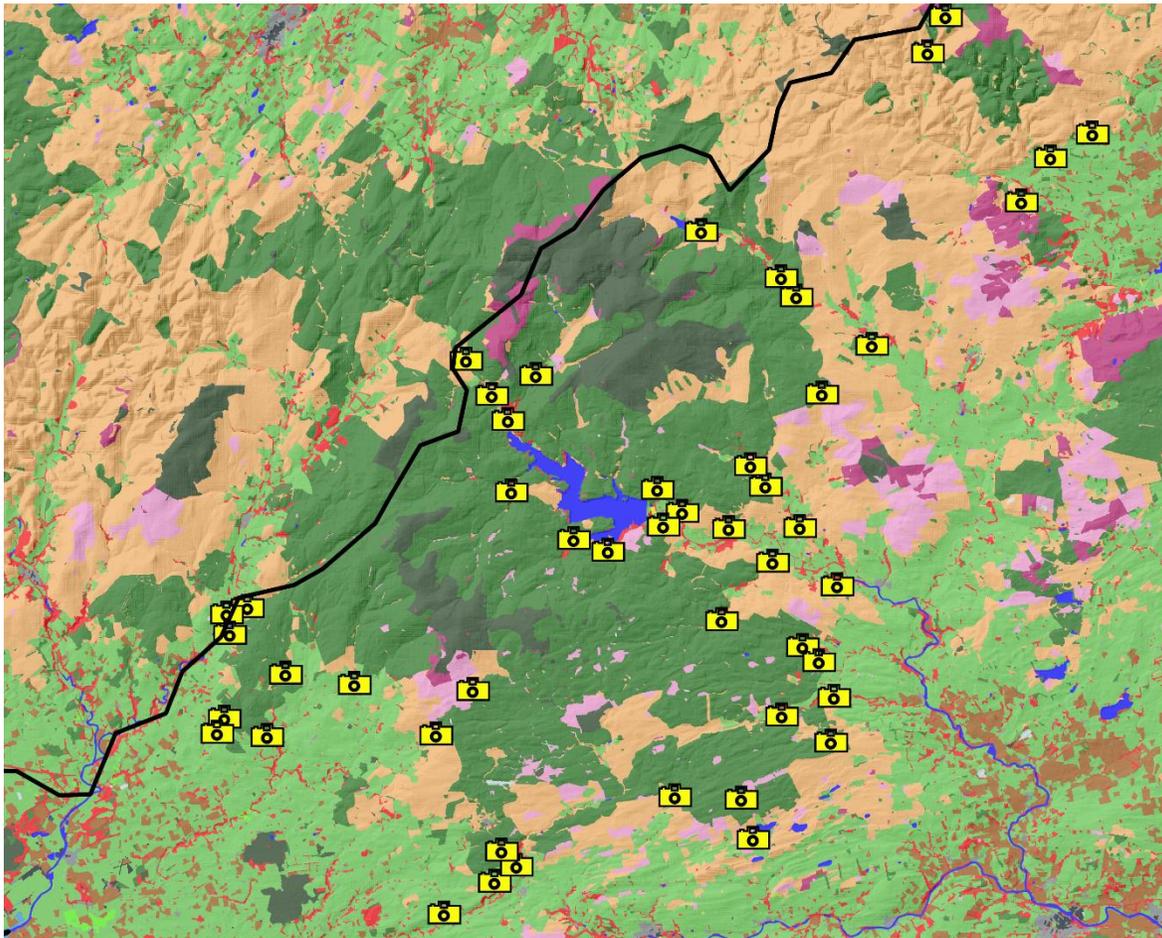
Land Cover Map 2015

- Broadleaved woodland
- Coniferous woodland
- Arable and Horticulture
- Improved Grassland
- Neutral Grassland
- Calcareous Grassland
- Acid Grassland
- Fen, Marsh and Swamp
- Heather
- Heather grassland
- Bog
- Inland Rock
- Saltwater
- Freshwater
- Supra-littoral Rock
- Supra-littoral Sediment
- Littoral Rock
- Littoral sediment
- Saltmarsh
- Urban
- Suburban
- En - Sc Borderline



- **LCM 2015** classification at 25m resolution
- Largest Human-made woodland complex in England
ca. 80% Conifer: mainly Sitka and Norway Spruce
- High landscape fragmentation and heterogeneity
- **Patchy landscape**

Camera Traps Network



NWT's Early Warning Detection System

- **50** Camera Traps across Kielder Forest since 2012
- Spacing configuration **based on Expert – Opinion**

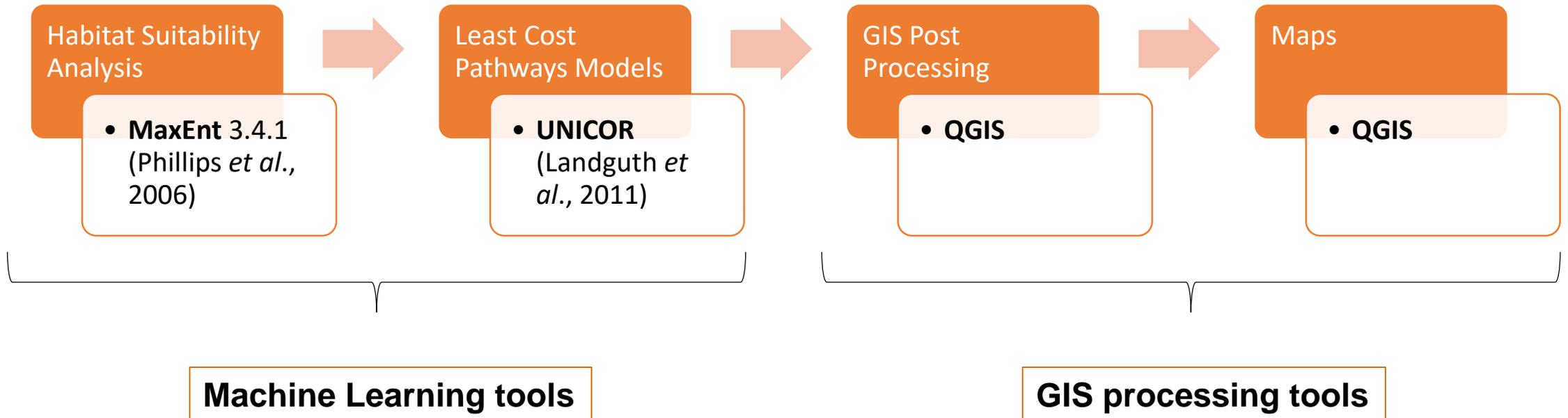
10 0 10 20 km



Aims of the study

- Identify the **most likely routes of movements of grey and red squirrels** across North England landscape and across South of Scotland, by developing Least Cost Pathways models (LCPs)
- Evaluate the **spatial configuration** of the camera traps network in order to figure out how well the monitoring programme is working and if changes are needed
- Identify **key areas** that might be **safeguarded from invasions**
- Identify **areas** where red squirrel **conservation efforts should be focused**
- Provide maps and tools useful to inform the management strategy
- Better understanding of the landscape use for grey and red squirrels

Analytical Process



Habitat Suitability Analysis



What it is?

Relationship between the occurrence record of a target species and the environment

Habitat Suitability Index : from **0** (*unsuitable habitat*) to **1** (*high suitable, optimal habitat*)

How?

MaxEnt Algorithm: Allow to compute a habitat suitability model using **presence only data**, demographic parameter (dispersal) and the **environmental variables** of the place where the species has been recorded

Why MaxEnt?



Widely used and well-accepted
presence – only modelling process

Data prepared in QGIS environment
at a resolution of **25m**



INPUT DATA

Red and Grey squirrel occurrence records

- RSNE annual monitoring system (2013 – 2018) - England
- NBN Atlas (2014 – 2018) - Scotland

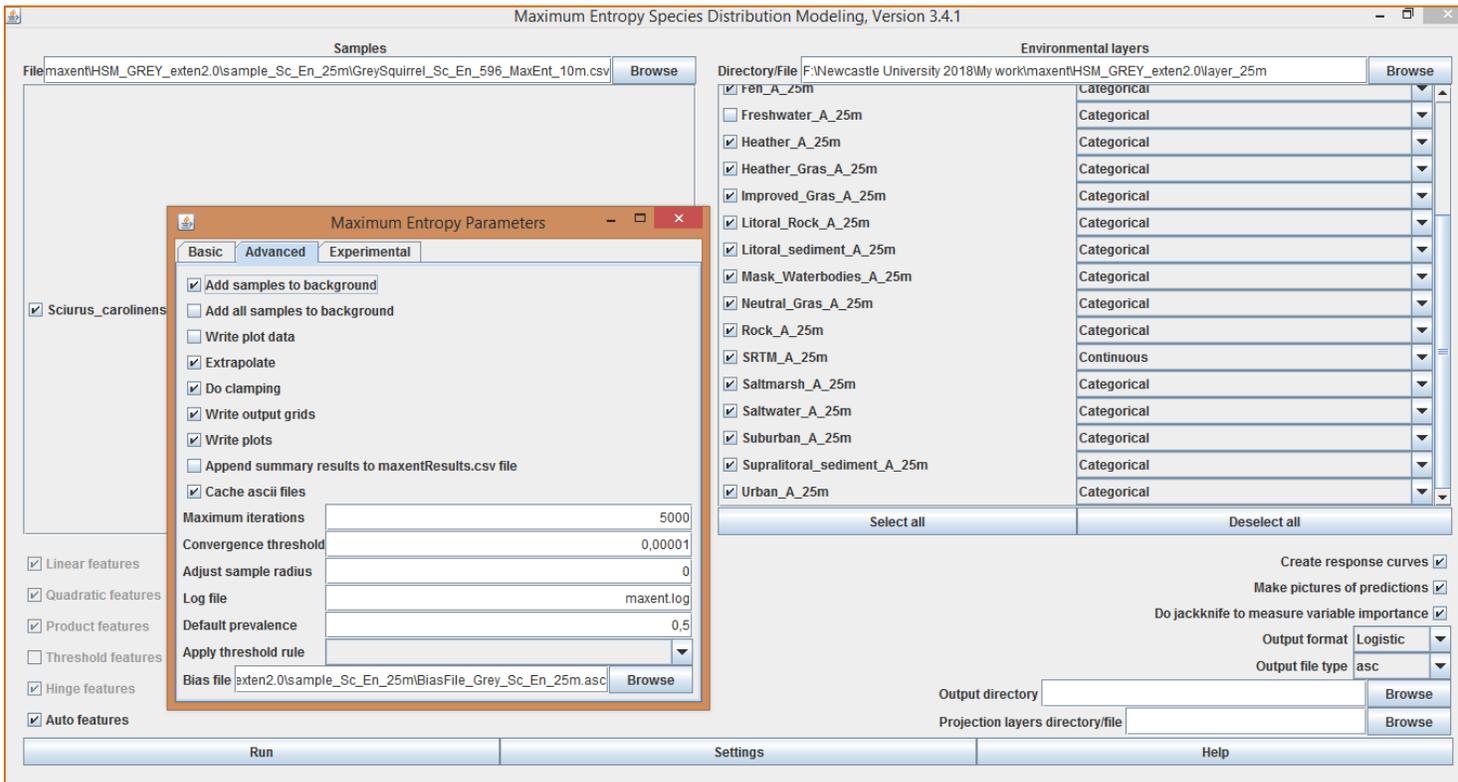
Environmental variable

- Land Cover Map 2015
- SRTM Altitude layer

Demographic parameter

- Dispersal

MaxEnt 3.4.1



- Occurrence records
- Environmental variables
- Background data default (10.000 points)
- Number of Maximum Interaction 5000
- Bias File (Sampling bias correction)
- **Logistic Output**



HSIndex = probability of presence
(under some circumstances)

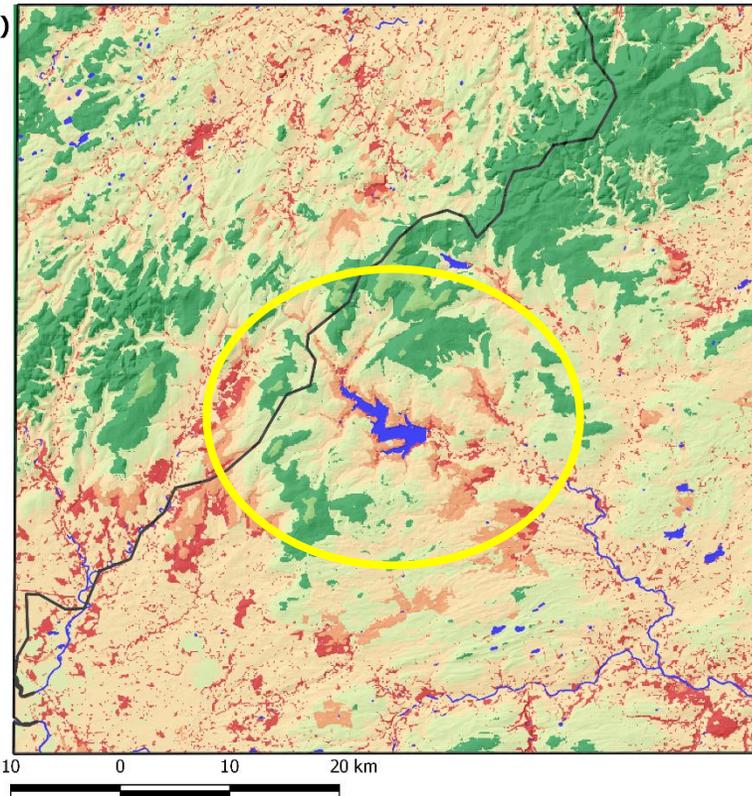
MaxEnt Outcomes



Habitat Suitability Map - Grey Squirrel

Habitat Suitability Index (HSI)

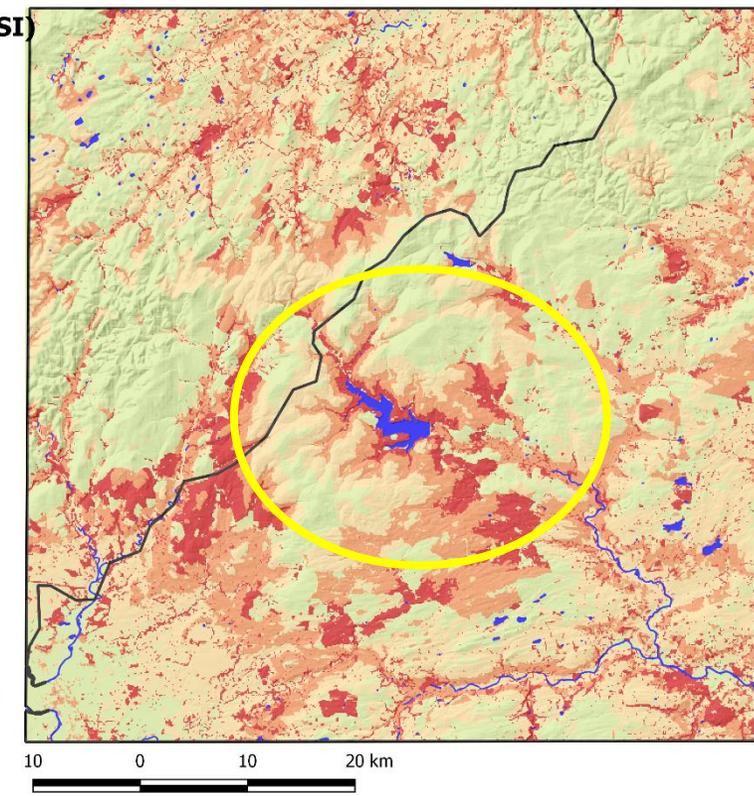
- ≤ 0.1
- 0.1 - 0.2
- 0.2 - 0.4
- 0.4 - 0.6
- 0.6 - 0.8
- 0.8 - 1
- Water bodies
- EnSc_Borderline



Habitat Suitability Map - Red squirrel

Habitat Suitability Index (HSI)

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Least Cost Pathway



What it is?

Least Cost Pathway models are tools to identify the most likely used routes of a species between presence points across the landscape

Widely used as **landscape connectivity** tool, for mapping **ecological corridors** and to predict animal movements

UNICOR

(Universal Corridor Network Simulator)



What it is?

Species connectivity and corridor identification tool (Landguth *et al.*, 2011)

What it does?

Compute a **single path** or **all the shorter paths** between points on a landscape, to create a **connectivity graph** which can be used to highlight:

- Least Cost Pathways
- Bottleneck
- Areas of high connectivity
- Ecological barriers

UNICOR

(Universal Corridor Network Simulator)



How it works?

UNICOR requires two input files:

1. Species **presence points** (nodes) – Start and End points between paths
2. Landscape **Resistance surface**



Is a cost-surface where each pixel is given a weight (**resistance value**) which represents the “cost” of movement across that pixel

UNICOR (Universal Corridor Network Simulator)



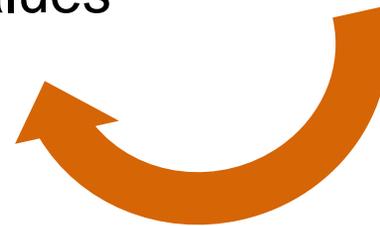
How to get the Resistance Surface?

Habitat Suitability Index **inversely linked** to the landscape Resistance



Higher habitat suitability values implies lower landscape resistance values and lower habitat suitability values refers to higher resistance values

Reciprocal Cubic Function of the Habitat Suitability Index for each pixel of the Habitat Suitability map



UNICOR Outcomes



Connectivity network composed of multiple paths in which each represent a **likely corridor of movement with different strength depending on the cost of moving** within the landscape across the resistance surface

QGIS Post Processing:

- The whole connectivity network over the Resistance surface
- The main and strongest connections
- Bottlenecks and areas of high connectivity – (Connectivity Density)
- Early warning detection system over the Least Cost Pathways map

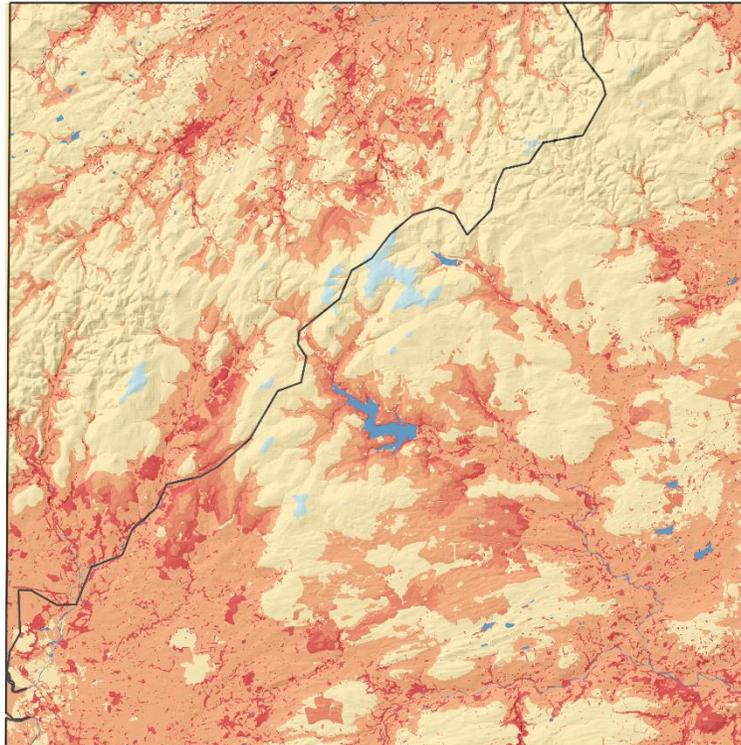
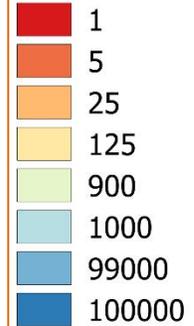
Resistance Surface



Landscape Resistance Surface Grey Squirrel

EnSc_Borderline

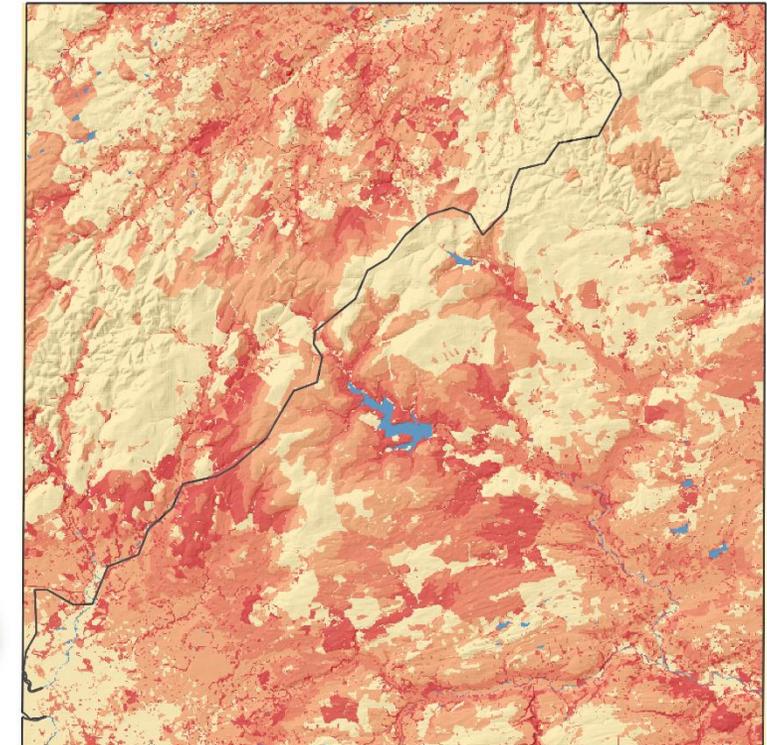
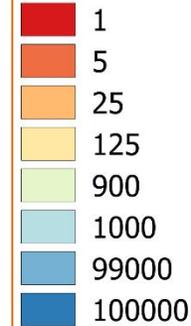
Resistance Values



Landscape Resistance Surface Red Squirrel

EnSc_Borderline

Resistance Values



Resistance Surface

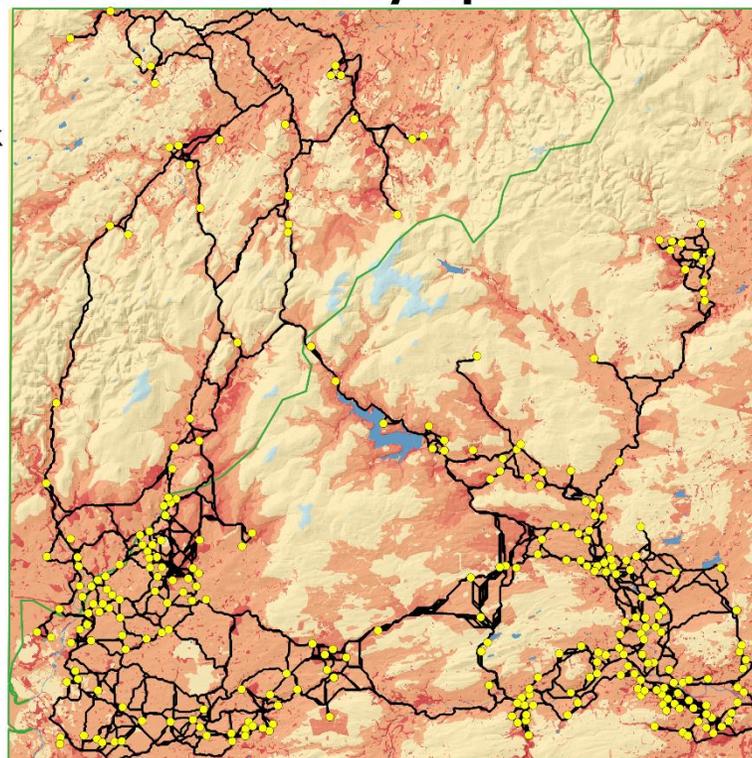


Landscape Resistance Surface Grey Squirrel

- Presence Points
- EnSc_Borderline
- Least Cost Network

Resistance Values

- 1
- 5
- 25
- 125
- 900
- 1000
- 99000
- 100000



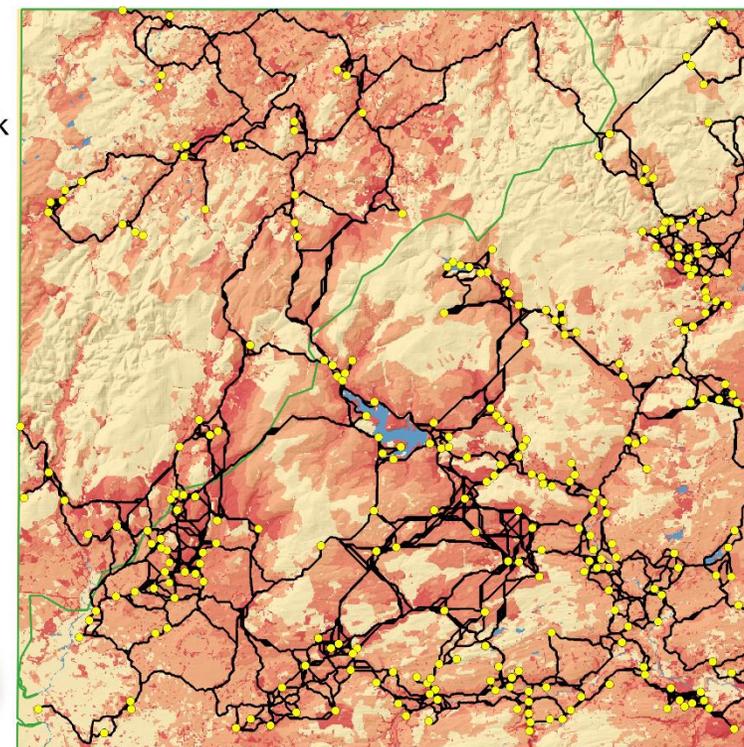
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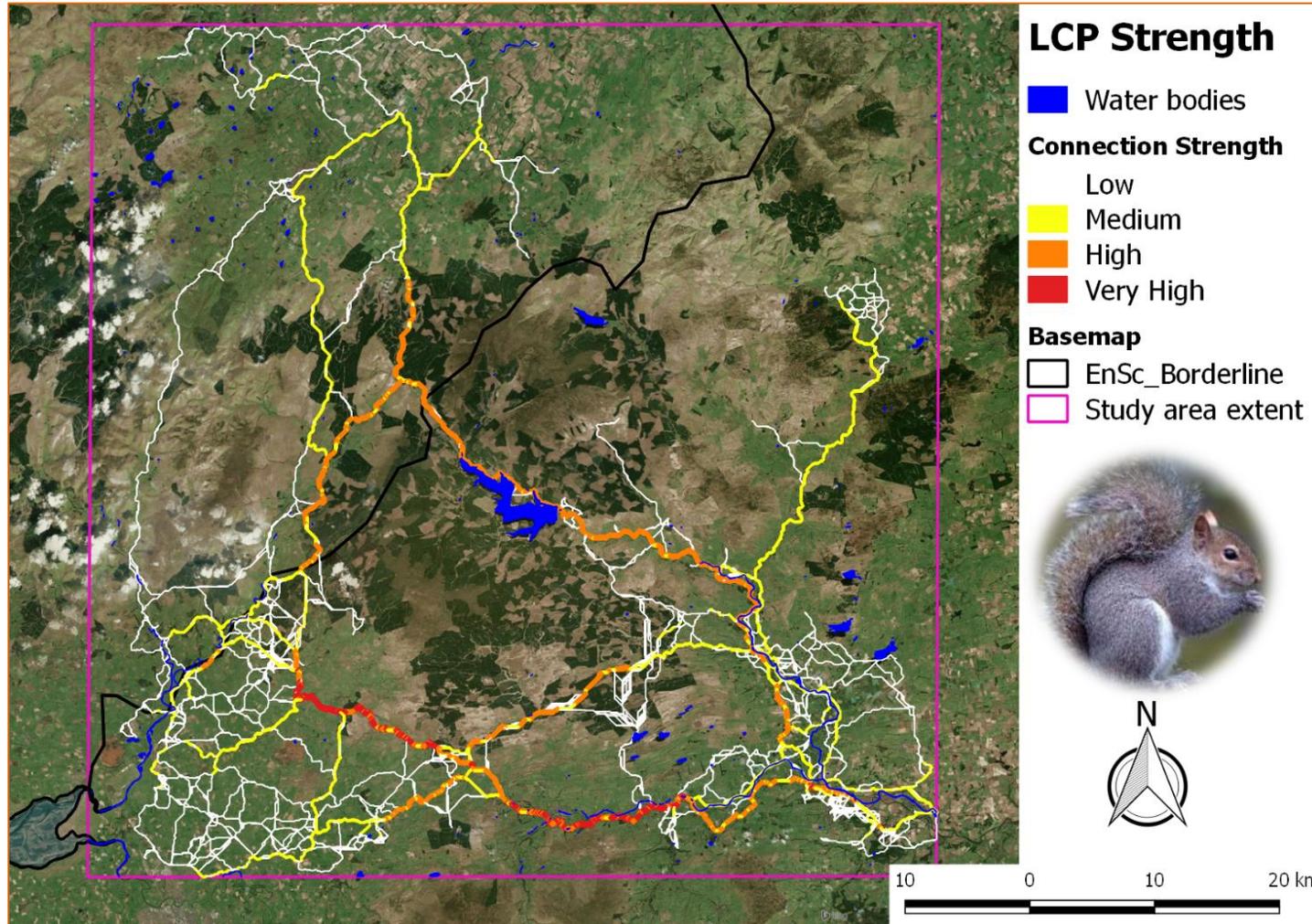
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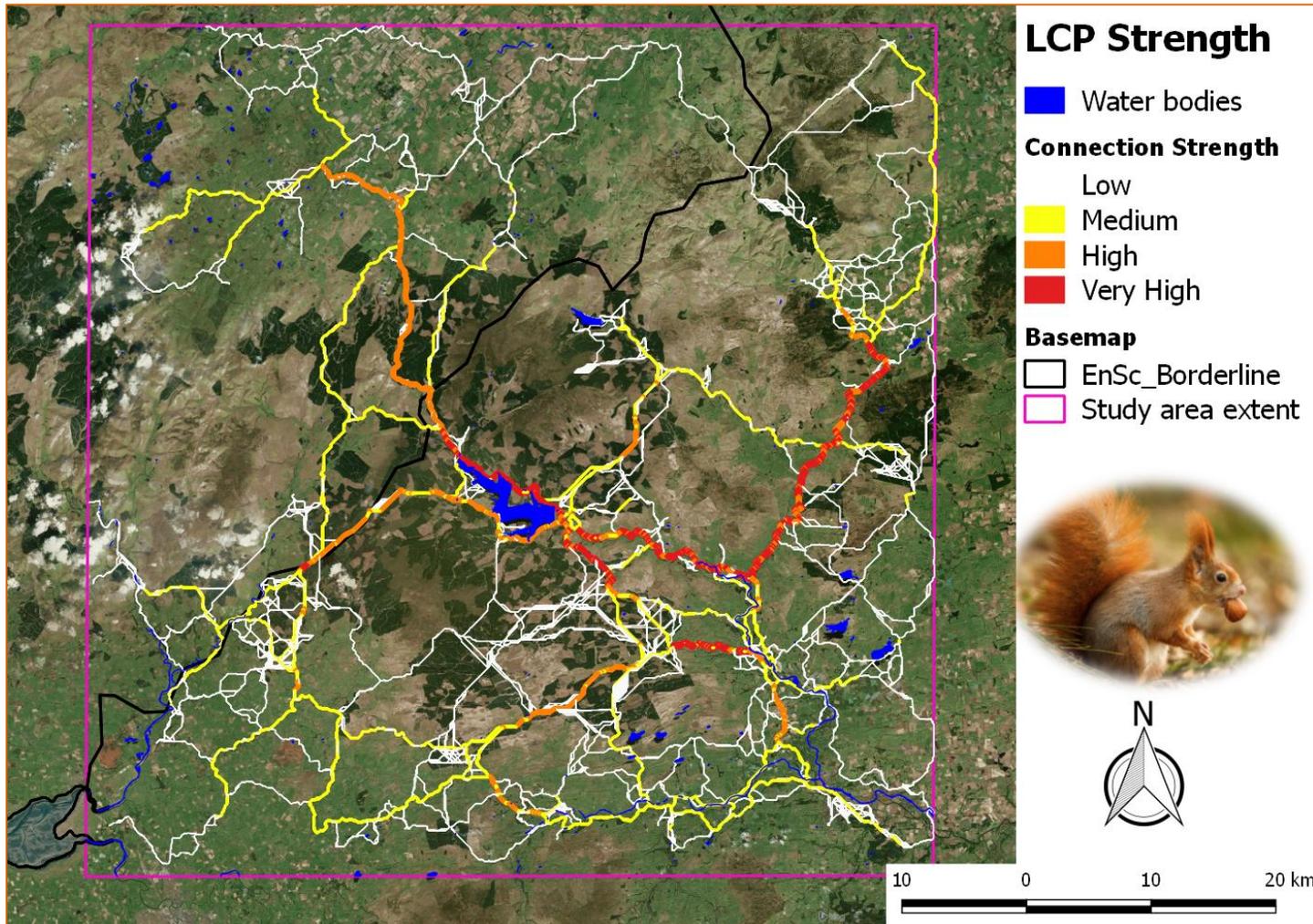


10 0 10 20 km

Strongest Least Cost connections



Strongest Least Cost connections



Connectivity Density Analysis



- **Bottlenecks**
- **Areas of High Connectivity**

Connectivity Density Analysis

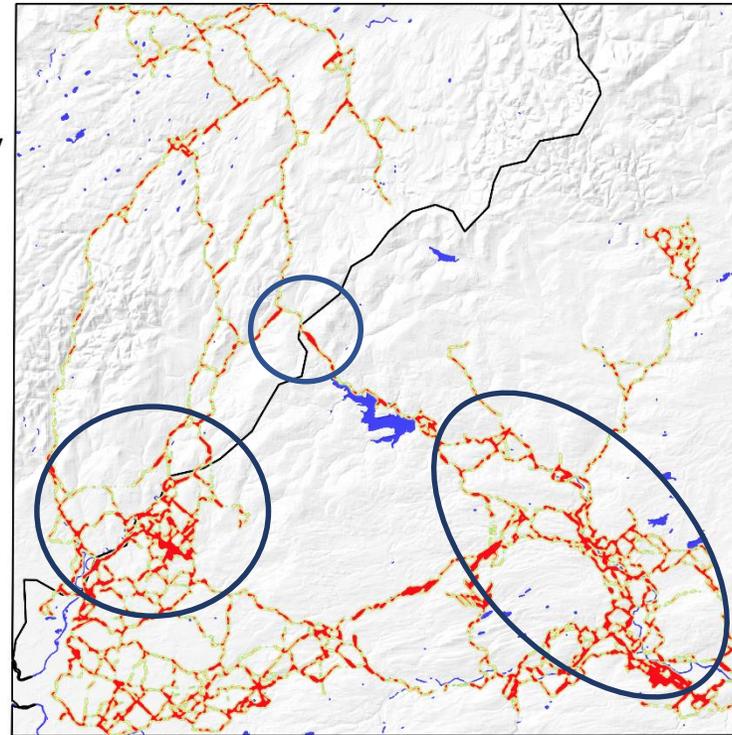


Connectivity Density Grey Squirrel

- EnSc_Borderline
- Water bodies

Connectivity Density

- Low
- Limited
- Moderate
- High
- Very high

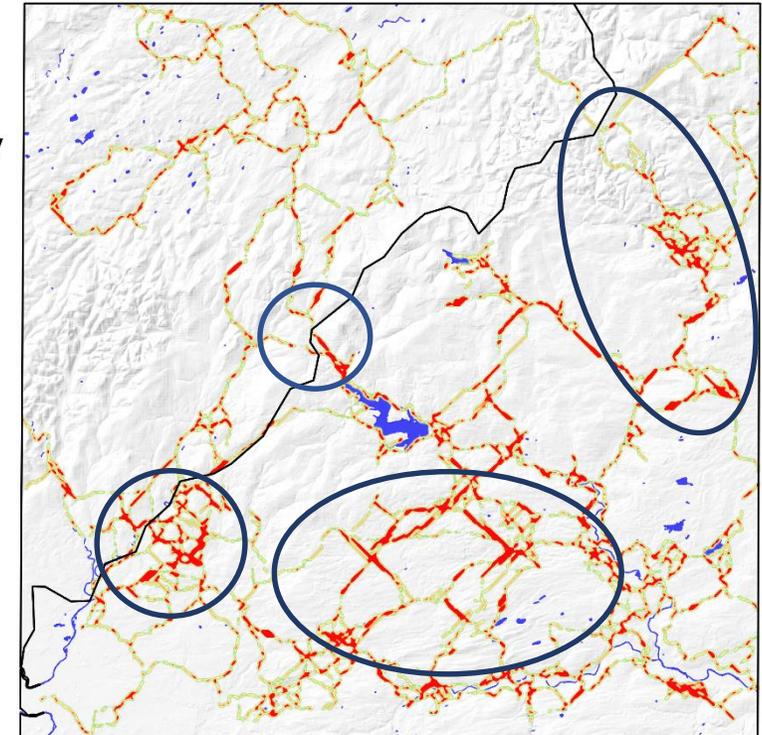


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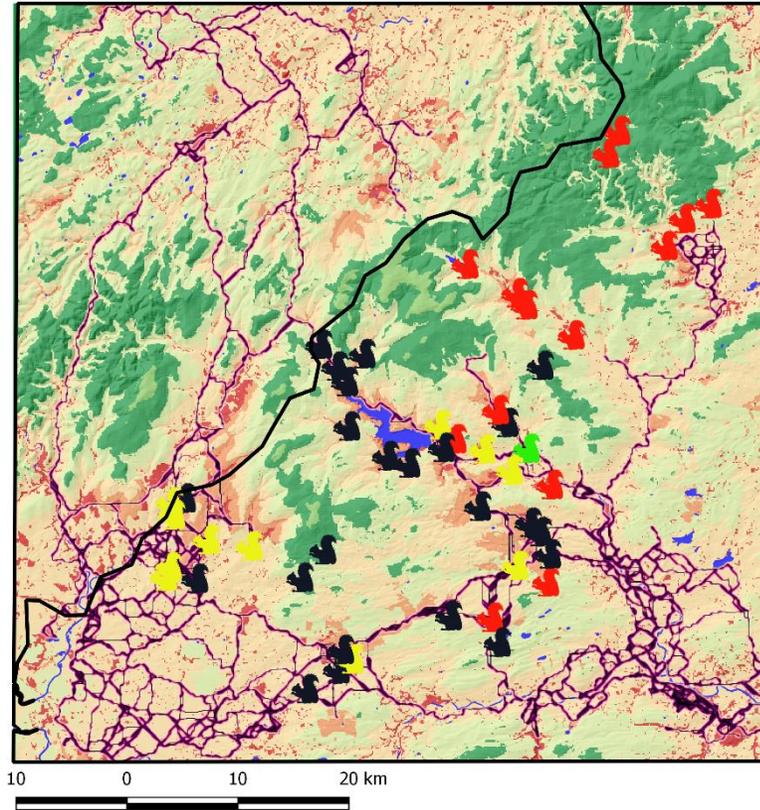
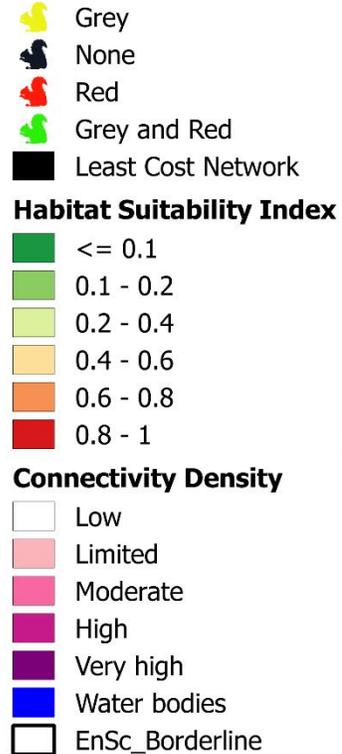
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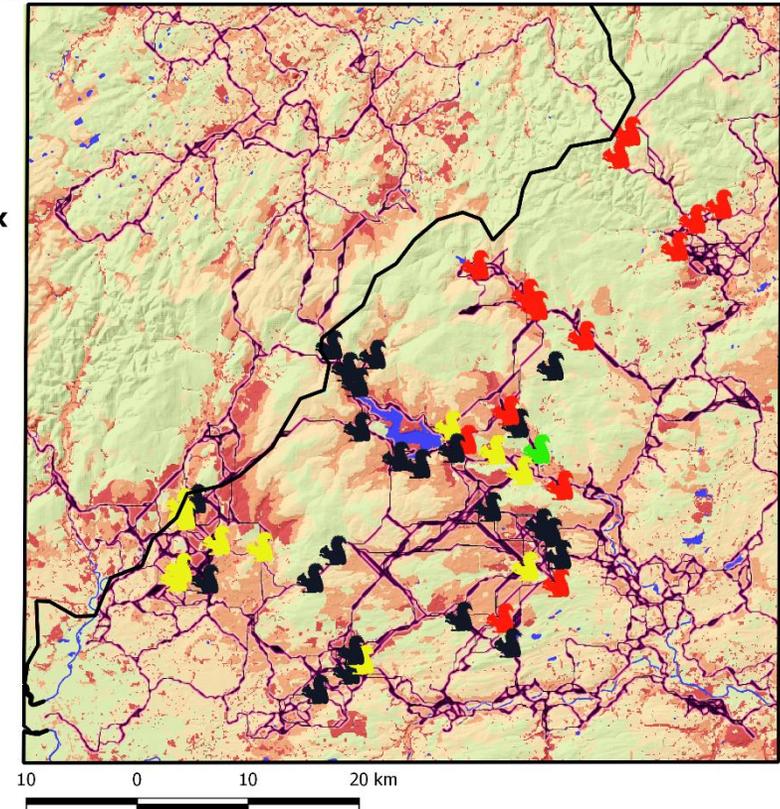
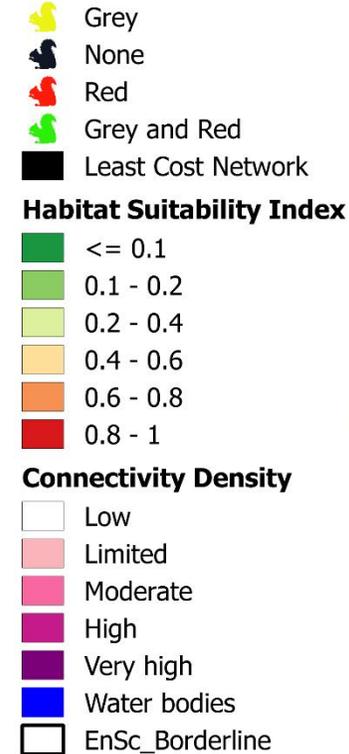
Early Warning Detection System



Squirrel Observed_QMOct17



Squirrel Observed_QMOct17



Squirrel Observed_QMOct17

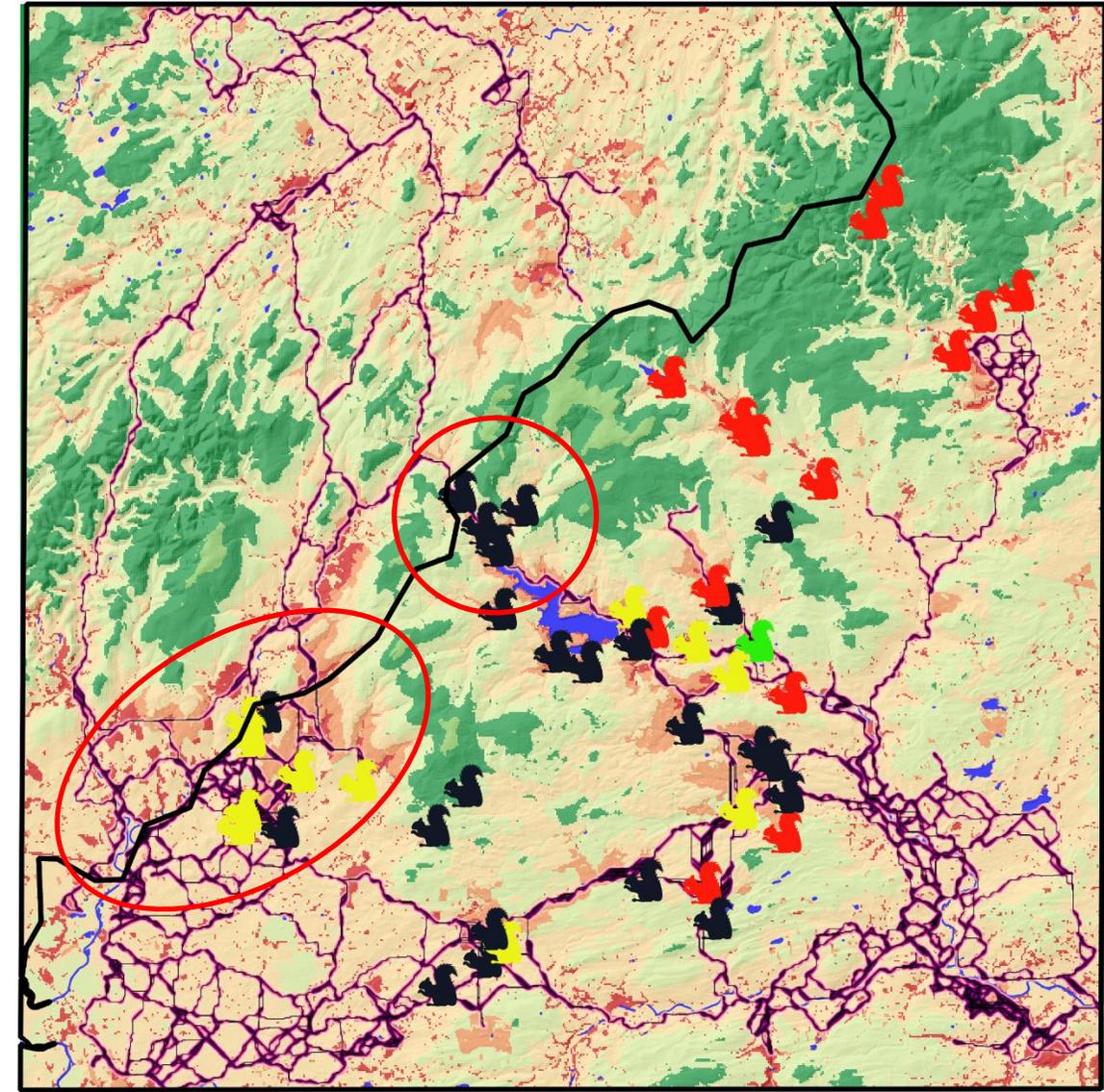
-  Grey
-  None
-  Red
-  Grey and Red
-  Least Cost Network

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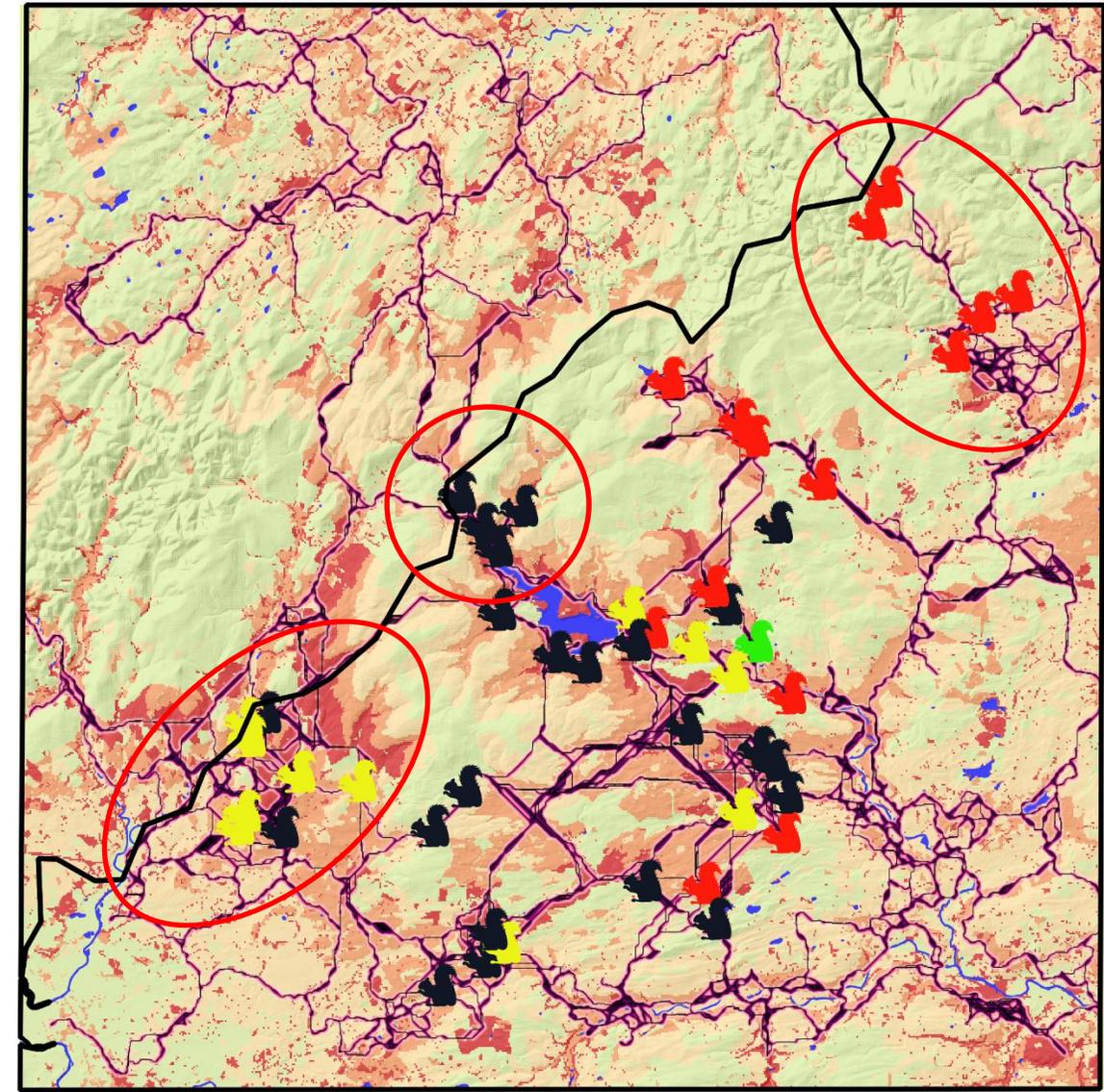
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Conclusion



1. Kielder Forest is an optimal habitat for red squirrel, but it is still well permeable to grey squirrel invasions
2. Landscape around Kielder Forest is well connected and the strongest connections for grey squirrel follows the two main river valleys
3. Areas of high connectivity density shows where control / monitoring efforts should be focused in preventing and detecting new invasions at an early stage
4. Three areas of high importance on the borderline with the South of Scotland that need to be defended from invasions coming from the North
5. Camera traps network falls into the predicted corridors used by squirrels
6. The Machine Learning approach gave value to the Expert-Opinion based approach in evaluating the spatial configuration of the detection system
7. Maps and tools useful to practitioners to improve the monitoring system
8. Driving the making-decision process to address the best monitoring strategy
9. Surveys into the main block of woodland in Kielder Forest may be useful to improve the model
10. A strict collaboration between English and Scottish partners is highly recommended

Acknowledgments

Modelling Evidence and Policy at Newcastle University



Red Squirrel Northern England



Saving Scotland's Red Squirrel



RSU Knowledge Fair 2019



Thank you!



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